

Response under a general periodic force

If the forcing function is periodic, we can use the Fourier series and the principle of superposition to get the response. The Fourier series states that a periodic function can be represented as a series of sines and cosines:

$$F(t) = \frac{a_0}{2} + a_1 \cos \omega t + a_2 \cos 2\omega t + \dots + b_1 \sin \omega t + b_2 \sin 2\omega t + \dots$$

$$= \frac{a_0}{2} + \sum_{j=1}^{\infty} a_j \cos j\omega t + b_j \sin j\omega t$$

$$a_j = \frac{2}{T} \int_0^T F(t) \cos(j\omega t) dt \quad , \quad j = 0, 1, 2, \dots$$

$$b_j = \frac{2}{T} \int_0^T F(t) \sin(j\omega t) dt \quad , \quad j = 1, 2, 3, \dots$$

where $T = 2\pi/\omega$ is the period. Now the equation of motion can be written as:

$$m\ddot{x} + c\dot{x} + kx = F(t) = \frac{a_0}{2} + \sum_{j=1}^{\infty} a_j \cos j\omega t + b_j \sin j\omega t$$

Using the principle of superposition, the steady-state solution of this equation is the sum of the steady-state solutions of:

$$m\ddot{x} + c\dot{x} + kx = \frac{a_0}{2}$$

$$m\ddot{x} + c\dot{x} + kx = a_j \cos j\omega t$$

$$m\ddot{x} + c\dot{x} + kx = b_j \sin j\omega t$$

The particular solution of the 1st equation is:

$$x_p(t) = \frac{a_0}{2k}$$

The particular solutions of the 2nd and 3rd equations are:

$$x_p(t) = \frac{a_j/k}{\sqrt{(1-j^2r^2)^2 + (2\zeta jr)^2}} \cos(j\omega t - \phi_j)$$

$$x_p(t) = \frac{b_j/k}{\sqrt{(1-j^2r^2)^2 + (2\zeta jr)^2}} \sin(j\omega t - \phi_j)$$

$$\phi_j = \tan^{-1}\left(\frac{2\zeta jr}{1-j^2r^2}\right)$$

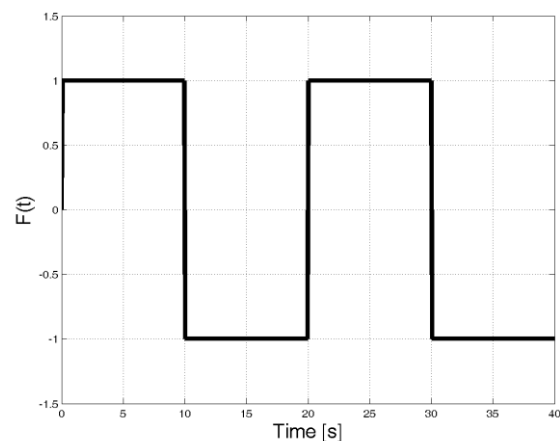
$$r = \frac{\omega}{\omega_n}$$

Then add up all the sums to get the complete steady-state solution as:

$$x_p(t) = \frac{a_o}{2k} + \sum_{j=1}^{\infty} \frac{a_j/k}{\sqrt{(1-j^2r^2)^2 + (2\zeta jr)^2}} \cos(j\omega t - \phi_j) + \sum_{j=1}^{\infty} \frac{b_j/k}{\sqrt{(1-j^2r^2)^2 + (2\zeta jr)^2}} \sin(j\omega t - \phi_j)$$

Observe that if $j\omega = \omega_n$, the amplitude will be significantly large, especially for small j and ζ . Further, as j becomes large, the amplitude becomes smaller and the corresponding terms tend to zero. How many terms do you need to include?

Example: Obtain the steady-state response of a dynamic system having $m=1$, $c=0.7$ and $k=1$ when subjected to the force shown.



Solution: here we have:

$$T = 20 \quad , \quad \omega = 2\pi/T = 2\pi/20 = \pi/10$$

and the forcing function is given by:

$$F(t) = 1 \quad 0 \leq t \leq 10$$

$$F(t) = -1 \quad 10 \leq t \leq 20$$

The Fourier series of the forcing function is given by:

$$F(t) = \frac{a_0}{2} + a_1 \cos \omega t + a_2 \cos 2\omega t + \dots + b_1 \sin \omega t + b_2 \sin 2\omega t + \dots$$

To get the constants, we have:

$$a_0 = \frac{2}{T} \int_0^T F(t) dt = \frac{2}{20} \left[\int_0^{10} dt - \int_{10}^{20} dt \right] = 0.1 [10 - (20 - 10)] = 0$$

$$\begin{aligned} a_j &= \frac{2}{T} \int_0^T F(t) \cos(j\omega t) dt \\ &= \frac{2}{20} \left[\int_0^{10} \cos\left(j \frac{\pi}{10} t\right) dt - \int_{10}^{20} \cos\left(j \frac{\pi}{10} t\right) dt \right] \\ &= 0.1 \left[\frac{10}{j\pi} \sin j \frac{\pi}{10} t \Big|_0^{10} - \frac{10}{j\pi} \sin j \frac{\pi}{10} t \Big|_{10}^{20} \right] = 0 \end{aligned}$$

i.e. all cosine terms vanish

$$\begin{aligned} b_j &= \frac{2}{T} \int_0^T F(t) \sin(j\omega t) dt \\ &= \frac{2}{20} \left[\int_0^{10} \sin\left(j \frac{\pi}{10} t\right) dt - \int_{10}^{20} \sin\left(j \frac{\pi}{10} t\right) dt \right] \\ &= 0.1 \left[\frac{-10}{j\pi} \cos j \frac{\pi}{10} t \Big|_0^{10} - \frac{-10}{j\pi} \cos j \frac{\pi}{10} t \Big|_{10}^{20} \right] \\ &= 0.1 \left[\frac{-10}{j\pi} (\cos j\pi - 1) + \frac{10}{j\pi} (\cos 2j\pi - \cos j\pi) \right] \end{aligned}$$

If j is odd,

$$b_j = 0.1 \left[\frac{-10}{j\pi}(-2) + \frac{10}{j\pi}(2) \right] = \frac{4}{j\pi}$$

If j is even,

$$b_j = 0.1 \left[\frac{-10}{j\pi}(0) + \frac{10}{j\pi}(0) \right] = 0$$

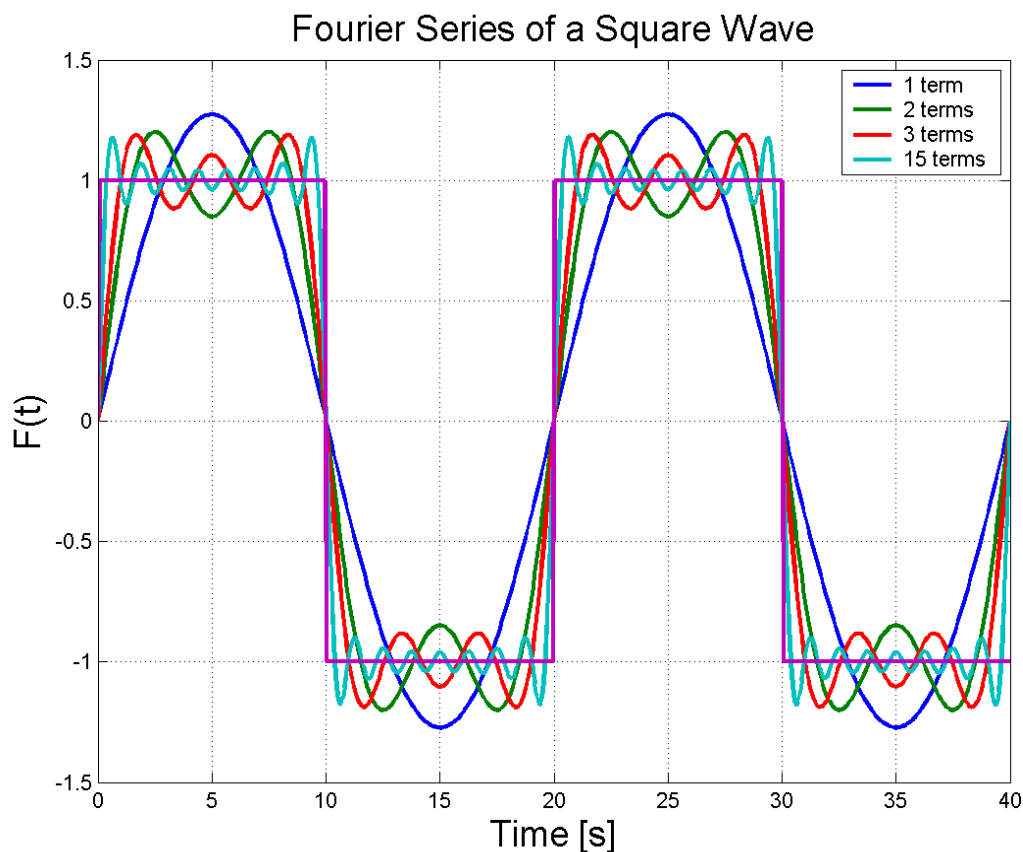
i.e. all even terms vanish.

In this way, the force can be represented by a Fourier series as:

$$F(t) = b_1 \sin \omega_1 t + b_3 \sin \omega_3 t + b_5 \sin \omega_5 t + \dots = \sum_{j=1}^{\infty} b_j \sin(j\omega t) \quad , \quad j = 1, 3, 5, 7, \dots$$

$$= \frac{4}{\pi} \sin \frac{\pi}{10} t + \frac{4}{3\pi} \sin \frac{3\pi}{10} t + \frac{4}{5\pi} \sin \frac{5\pi}{10} t + \dots = \sum_{j=1}^{\infty} \frac{4}{j\pi} \sin \left(j \frac{\pi}{10} t \right) \quad , \quad j = 1, 3, 5, 7, \dots$$

or graphically as:



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% *****
% Periodic response of a dynamic system to a square input waveform
% *****
clear; close all;
m=1; c=0.7; k=1; % Parameters

wn=sqrt(k/m); zi=c/wn/2; w=pi/10;

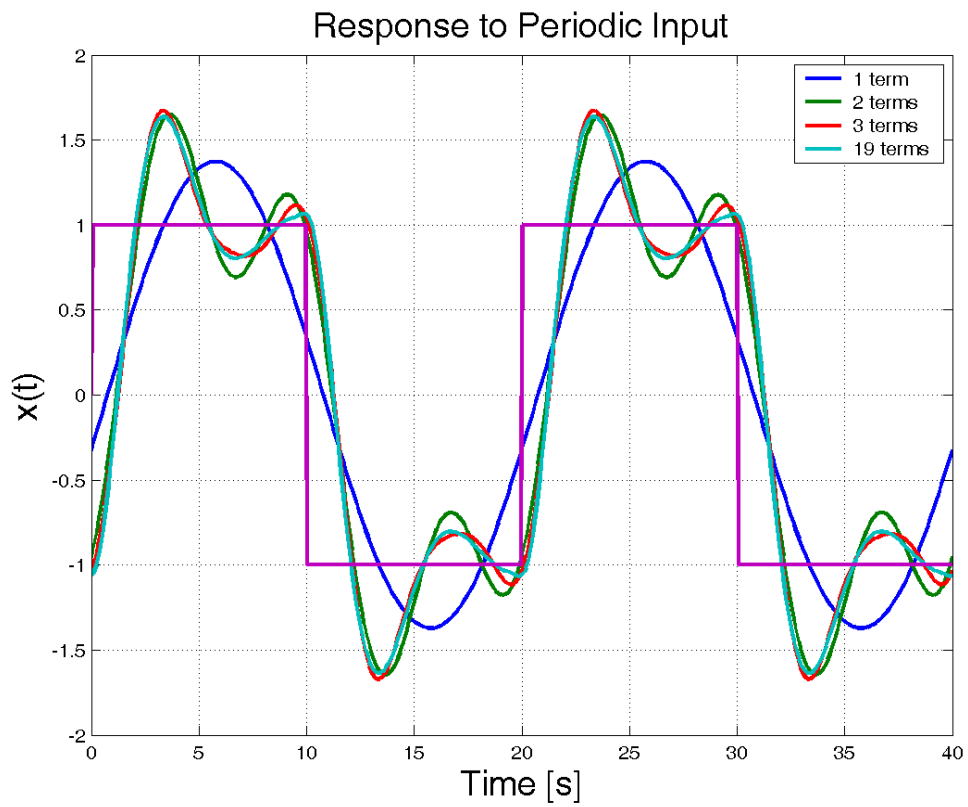
t=linspace(0,40,500); x=zeros(size(t)); r=w/wn;
for jj=1:2:19
    a(jj)=4/pi/jj;
    X(jj)=a(jj)/k/sqrt((1-jj^2*r^2)^2+(2*zi*jj*r)^2); % term in summation
    phi(jj)=atan2(2*zi*jj*r,1-jj*jj*r*r);
    x(jj+2,:)=x(jj,:)+X(jj)*sin(w*jj*t-phi(jj));
end
u=sign(sin(w*t));

figure(1)
plot(t,x([3 5 7 21],:),t,sign(sin(w*t)),'linewidth',2);grid
legend('1 term','2 terms','3 terms','19 terms')
xlabel('Time [s]','fontsize',18);ylabel('x(t)','fontsize',18)
title('Response to Periodic Input','fontsize',18);

figure(2)
plot(1:2:19,X(1:2:19),'o','markersize',10,'linewidth',4);grid
ylabel('Magnitude of term in summation','fontsize',18)
xlabel('Summation term','fontsize',18)

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The system response is shown below:



The contribution of each term in the summation is determined from:

